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Enhanced Vector Field Visualization via Lagrangian Accumulation

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ABSTRACT

In this paper, we revisit the *Lagrangian accumulation* process that aggregates the local attribute information along integral curves for vector field visualization. Similar to the previous work, we adopt the notation of the Lagrangian accumulation field or \mathscr{A} field for the representation of the accumulation results. In contrast to the previous work, we provide a more in-depth discussion on the properties of \mathscr{A} fields and the meaning of the patterns exhibiting in \mathscr{A} fields. In particular, we revisit the discontinuity in the \mathscr{A} fields and provide a thorough explanation of its relation to the flow structure and the additional information of the flow that it may reveal. In addition, other remaining questions about the \mathscr{A} field, such as its sensitivity to the selection of integration time, are also addressed. Based on these new insights, we demonstrate a number of enhanced flow visualizations aided by the accumulation framework and the \mathscr{A} fields, including a new \mathscr{A} field guided ribbon placement, a \mathscr{A} field guided stream surface seeding and the visualization of particle-based flow data. To further demonstrate the generality of the accumulation framework, we extend it to the non-integral geometric curves (i.e. streak lines), which enables us to reveal information of the flow behavior other than those revealed by the integral curves. Finally, we introduce the Eulerian accumulation, which can reveal different flow behavior information from those revealed by the Lagrangian accumulation. In summary, we believe the Lagrangian accumulation and the resulting \mathscr{A} fields offer a valuable way for the exploration of flow behaviors in addition to the current state-of-the-art techniques.

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patterns, in order to reduce the information overloading (i.e. clutter) and occlusion issue. These two goals are some time conflicting with each other, especially when visualizing high dimensional flows.

Geometric-based visualization is often applied to achieve a 18 tradeoff of the above two conflicting goals. On the one hand, 19 continuous and smooth geometric representations (e.g. integral 20 curves/surfaces) effectively depict the spatio-temporal coher-21 ence nature of vector fields. On the other hand, these geometric 22 representations enable the encoding of other flow characteris-23 tics than the directional information via color, transparency and 24 texture. To the extreme, full spatial coverage (Goal 1) may be 25 achieved via densely placed integral curves - the intrinsic geo-26 metric descriptor of flows, which will certainly result in severe 27

1 1. Introduction

Vector field visualization is a ubiquitous technique that is employed to study a wide range of dynamical systems involved in applications, such as automobile and aircraft engineering, climate study, combustion dynamics, earthquake engineering, and medicine, among others. Many effective approaches have been developed to visualize these complex data [1, 2, 3, 4]. There are in general two goals for flow visualization: (1) achieve sufficient spatial coverage and (2) reveal salient flow patterns of interest. The former goal aims to display flow information 10 in possibly every spatial (or spatio-temporal) location to avoid 11 missing any important flow behaviors. The latter seeks to iden-12 tify and display (or highlight) certain important (or salient) flow 13





occlusion and clutter issue. To alleviate that, texture-based visualization techniques [5, 6] convolve randomly assigned colors along the integral curves (e.g. streamlines) to introduce 3 enough variance between neighboring streamlines in terms of color to depict the flow patterns in a dense fashion. In a sim-5 ilar spirit, certain accumulated attributes along integral curves 6 have been used to help classify and select integral curves of 7 interest from the densely placed integral curves to reduce the 8 occlusion and clutter in visualization [7, 8, 9, 10, 11]. One a example of these techniques is the accumulation of the wind-10 ing angles along streamlines for the identification of vortex re-11 gions [12]. In fact, both the above convolution processes used 12 in the texture-based visualization and the attribute accumulation 13 in integral curve exploration are essentially an accumulation (or 14 aggregation) of quantities along integral curves, which we refer 15 16 to as the Lagrangian accumulation.

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18 Problem description.

Zhang et al. [13, 14] recently extended the above Lagrangian 19 accumulation to define a derived field based on the accumulated 20 values along integral curves. Briefly, the information – usually 21 22 some local flow characteristics, along each integral curve is aggregated onto its starting point, allowing the representation of 23 this Lagrangian information (i.e. along integral curves) in an 24 Eulerian fashion (i.e. at their starting points). The derived field, 25 also referred to as the attribute field, denoted by \mathscr{A} , is used to 26 help identify the discontinuity in the behaviors of the neighbor-27 ing integral curves [13] and perform segmentation of the flow 28 domain [15], respectively. However, there are still a number of 29 unsolved problems with this original Lagrangian accumulation. 30

First, the characteristics and behaviors of \mathscr{A} are not well un-31 derstood. There still lacks a thorough discussion on what is 32 actually shown or encoded in \mathscr{A} . Although there is limited dis-33 cussion on the potential connection between the discontinuity 34 in \mathcal{A} and the vector field topology [13], their relation is yet to 35 be clarified. In addition, the computation of \mathscr{A} requires to set 36 the length of the integration. How does this parameter affect the 37 behaviors of \mathscr{A} is unclear. Addressing all the above questions 38 is crucial to determine under what circumstances that \mathscr{A} can 39 be useful to assist the tasks of vector field analysis and explo-40 ration and how to appropriately utilize \mathscr{A} without introducing 41 mis-leading information. 42

Second, it has also been mentioned in [13, 14] that different 43 As computed based on different flow characteristics may ex-44 hibit different behaviors (or patterns). However, there is no a 45 thorough discussion on what characteristics of the vector field 46 the A computed from a selected attribute can reveal. Under-47 standing this is important to instruct the user in the considera-48 tion of the appropriate attribute for the computation of \mathscr{A} . Fur-49 thermore, a better understanding to the similarity/dissimilarity 50 51 between As computed using different attributes will provide additional information to the study of the possible causal rela-52 tions among attributes. 53

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To address the above remaining and critical issues, this work makes the following contributions:

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- We provide a more in-depth discussion on the properties of \mathscr{A} fields and the meaning of the patterns exhibiting in \mathscr{A} fields. In particular, we revisit the discontinuity in the \mathscr{A} fields and provide a thorough explanation of its relation with the flow structure and the additional information that it may reveal. Other remaining questions about the \mathscr{A} fields, such as its sensitivity to the selection of integration time, are also discussed.
- We propose a number of enhanced flow visualizations aided by \mathscr{A} fields, including a new \mathscr{A} field guided ribbon placement, a \mathscr{A} field guided stream surface seeding and the visualization of particle-based flow data. We have applied these enhanced visualizations to a number of 2D/3D steady/unsteady flow data.
- We provide an informal study of the relation among different attributes, which we hope may enlighten the selection of the appropriate attributes for the accumulation to meet different needs.
- We extend the previous accumulation along integral curves to the non-integral geometric curves (i.e. streak lines), which enables us to reveal information of the flow behavior different from those revealed by accumulating along integral curves.
- Finally, we introduce the Eulerian accumulation for unsteady flow data, which aggregates the local attribute information at fixed spatial location over time. This enables us to inspect the flow behavior from a different angle than the Lagrangian accumulation.

In summary, we believe the Lagrangian accumulation (or the general accumulation) and the resulting \mathscr{A} fields offer a valuable way to support the exploration of flow behaviors in addition to the current state-of-the-art techniques.

2. Related Work

There is a large body of literature on the analysis and visualization of flow data. Interested readers are encouraged to refer to recent surveys on the dense and texture-based visualization techniques [5], geometric-based methods [16], illustrative visualization [17], topology-based methods [2, 3], and partitionbased techniques [4], respectively. In this section, we focus on the most relevant work.

Dense and texture-based techniques Dense and texture-based 99 flow visualization techniques have been one of the most popu-100 lar methods that aim to reveal the flow directional information, 101 while achieving full spatial coverage at the same time. Based on 102 the survey [5], texture-based techniques can be classified into 103 LIC techniques [18, 19, 20, 21, 22] and advection (or warp-104 ing) based techniques [23, 24, 25]. The goal of both groups is 105 to make the output image having similar color along integral 106 curves, while with sufficiently different colors along the direc-107 tion that is perpendicular to the flow direction. Matvienko and 108

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Kruger [6] utilized this observation to study the inequality property of the generated texture images to evaluate their quality. In
this work, we study a similar inequality property of the resulting A fields computed by accumulating along integral curves.
In the meantime, dense visualization can be generated by measuring the density of the integral curves within any spatial unit,
such as the structure-accentuating dense flow visualization [26].
The obtained salient flow structure is typically around separation structure due to the strong convergence of flow there. In
this work, we discuss how this varying density of the integral
curves in the flow domain may influence the salient structure
ncoded in the A field.

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Lagrangian framework for flow analysis In fluid dynam-14 ics, there are two different views for the study of flow be-15 haviors, i.e., observing the flow at fixed location-Eulerian 16 point of view, or observing it on a moving particle-Lagrangian 17 point of view. In this work, we specifically focus on the 18 Lagrangian framework, which studies the behavior of parti-19 cles along their individual paths, i.e., integral curves computed 20 from the seeded positions. According to this characteristic, 21 the Finite-Time Lyapunov Exponent (FTLE) [27], the stream-22 line [9] and pathline [10] predicates, the pathline attribute ap-23 proaches [28, 8, 11], and the streamline and pathline dissimilar-24 25 ity for streamline clustering [29], selection [30], and the ensemble analysis [31] are all examples of Lagrangian approaches. 26 Among them, the FTLE approach aims to measure the rate of 27 flow separation at individual spatial sampling points. Its flow 28 map computation is essentially a special case of Lagrangian 29 accumulation (Section 3.2) that sums up all the vector values 30 scaled by the integration step size along the path of the particle, 31 which leads to the end position of a particle given its starting 32 position. This accumulation neglects all intermediate position 33 as well as other information of the particle that is not relevant 34 to the flow separation. The computed rate of separation at each 35 point is encoded as a scalar field, which facilitates the identifi-36 cation of its ridges-known as the Lagrangian Coherent Struc-37 ture (LCS). This Eulerian representation of the FTLE fields is 38 similar to our derived \mathscr{A} fields. Nonetheless, the Lagrangian 39 accumulation and the resulting \mathscr{A} fields are more general than 40 the FTLE approach, and can be used to encode attributes of the 41 particles along their paths rather than just at their starting and 42 ending positions. 43

The idea of accumulating local characteristics along the particle trajectories and assigning the accumulated values to the corre-45 sponding integral curves has been applied by the pathline at-46 tribute approaches. Specifically, Shi et al. [11] presented a data 47 exploration system to study the different characteristics of path-48 lines based on their various attributes. Pobitzer et al. [8] applied 49 a statistics-based method to select a proper subset of pathline 50 attributes to improve the interactive flow analysis. While not 51 directly accumulating the local attributes, Guo et al. [28] pro-52 posed to accumulate the square difference between the local at-53 tributes along pairs of integral curves to define the distance be-54 tween them. Recently, Zhang et al. [13, 14] extended the above 55 Lagrangian accumulation to define an attribute field based on 56

the accumulated values along integral curves. This attribute 57 field adopts the Eulerian representation of the Lagrangian in-58 formation, in a similar fashion to the texture-based technique, 59 which enables a continuous representation of the variation of 60 the integral curve behaviors to some extent. In contrast to the 61 previous work by Zhang et al., we provide a deeper discus-62 sion on the behaviors of the obtained attribute fields and extend 63 the Lagrangian accumulation to the accumulation along non-64 integral curves (i.e. streak lines). Furthermore, we introduce an 65 Eulerian accumulation framework. 66

More recently, Lagrangian representation has been introduced to address the scalability issue of the visualization of large scale unsteady flows [28, 32].

3. The Lagrangian Accumulation

In this section, we describe the Lagrangian accumulation and provide an in-depth discussion on its behavior under different selections of parameters. We also offer a thorough discussion on what can be revealed in the derived attribute fields from the accumulation. In the following, we start with a brief review of some important concepts of vector fields.

3.1. Vector Field Background

Consider a spatial domain $\mathbb{D} = \mathbb{M} \times \mathbb{R} \subset \mathbb{R}^3$, a general vector 78 field can be expressed as an ordinary different equation (ODE) 79 $\dot{\mathbf{x}} = \mathbf{v}(\mathbf{x};t)$. An integral curve (or trajectory) that is everywhere 80 tangent to \mathbf{v} is a solution to the initial value problem of the 81 above ODE system, denoted by $\mathbf{x}(t) = \mathbf{x}_0 + \int_0^t \mathbf{v}(\mathbf{x}(\tau); t_0 + \tau) d\tau$. 82 In the unsteady vector fields, an integral curve is also referred 83 to as a pathline, while in the steady case, it is called streamline. There are a few special streamlines in the steady flows. Stream-85 lines that degenerate to points are fixed points. They correspond 86 to places where $\mathbf{v} = 0$. Streamlines that form closed curves are 87 referred to as periodic orbits, together with fixed points, they define the vector field topology [33]. 89

Flow Attributes. Given a vector field **v**, its spatial gradient $\nabla_{\mathbf{x}} \mathbf{v}$ is referred to as its *Jacobian*, denoted by **J**. **J** can be decomposed as $\mathbf{J} = \mathbf{S} + \mathbf{R}$, where $\mathbf{S} = \frac{1}{2}[\mathbf{J} + (\mathbf{J})^{\top}]$ and $\mathbf{R} = \frac{1}{2}[\mathbf{J} - (\mathbf{J})^{\top}]$ are the symmetric and antisymmetric components of **J**, respectively. A number of flow attributes can be derived from **v**, **J**, **S** and **R** [8]. In this work, we utilize the following local attributes, a_l , for various experiments.

- a_1 : vorticity, $||\nabla \times \mathbf{v}||$.
- a_2 : divergence, $tr(\mathbf{J})$, i.e. trace of \mathbf{J} .
- a_3 : helicity, $\nabla \times \mathbf{v} \cdot \mathbf{v}$.
- a_4 : λ_2 , the second largest eigenvalue of the tensor $\mathbf{S}^2 + \mathbf{R}^2$ [34].
- $a_5: Q = \frac{1}{2} (\|\mathbf{R}\|^2 \|\mathbf{S}\|^2)$ [35].
- a_6 : local shear rate, the Frobenius norm of **S**.
- *a*₇: determinant of **J**.

- a_8 : change of flow direction (also known as winding angle), $\angle(\mathbf{v}(\mathbf{p}_i), \mathbf{v}(\mathbf{p}_{i+1}))$ where \mathbf{p}_i denotes a point on an integral curve. This geometric attribute essentially measures the curvature of the integral curve at \mathbf{p}_i .
- a_9 : velocity vector **v**.

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$$a_{10}$$
, acceleration, $\mathbf{a}(\mathbf{x},t) = \frac{D\mathbf{v}}{Dt} = \frac{\partial \mathbf{v}(\mathbf{x},t)}{\partial t} + (\mathbf{v}(\mathbf{x},t) \nabla)\mathbf{v}(\mathbf{x},t)$.

⁸ 3.2. Lagrangian Accumulation of Local Attributes

Consider an integral curve, \mathscr{C} , starting from a given point (\mathbf{x}, t_0) , the Lagrangian accumulation can be formulated as the following convolution process.

$$A_g((\mathbf{x},t_0),t) = \int_0^t k(\tau)a_l(\mathscr{C}(\tau),t_0+\tau)d\tau$$
(1)

where $k(\tau)$ is a filter kernel following the integral curves [18, 9 25]. For simplicity, in this work we assume a simple box fil-10 *ter* [21], for all examples. $a_l(\mathscr{C}(\tau), t_0 + \tau)$ is the value of the 11 selected local flow property a_l measured at location $\mathscr{C}(\tau)$ and at 12 time $t_0 + \tau$, which can be either scalar, vector, or tensor values. 13 For the later discussion, we mainly consider scalar properties. 14 In most cases, a_l is continuous in \mathbb{D} except at some special loca-15 tions, such as fixed points in the steady cases. $A_g((\mathbf{x}, t_0), t)$ rep-16 resents the accumulated value. $t \in \mathbb{R}$ is the integration window 17 size. Note that t can be negative to account for the backward in-18 tegration. In addition, considering both forward and backward 19 integration starting at (\mathbf{x}, t_0) is also possible. Nonetheless, we 20 21 will concentrate on the forward integration at this moment.

The above formulation works for the accumulation under the time-dependent settings. In the steady cases, the local attribute values are not dependent on the current integration time but only the location, i.e. denoted by $a_l(\mathscr{C}(\tau))$. More often, in the steady cases, the accumulation is performed with a specified length *s* along the streamlines.

$$A_g(\mathbf{x},s) = \int_0^s k(\boldsymbol{\eta}) a_l(\mathscr{C}(\boldsymbol{\eta})) d\boldsymbol{\eta}$$
(2)

Again, this accumulation along streamline can also be performed in both forward and backward directions. To simplify the subsequent discussion, we will refer to the Lagrangian accumulation as the *L*-accumulation for the rest of the paper.

Given a spatio-temporal domain $\mathbb{D} = \mathbb{M} \times \mathbb{T}$, a derived scalar 26 field can be obtained (assuming a_l is scalar) from the above 27 convolution, where the value at each sample position is deter-28 mined by Eq.(1) or (2). We refer to this field as a Lagrangian 29 Accumulation field or an \mathscr{A} field. The scalar fields discussed 30 in [36] are essentially the examples of \mathscr{A} fields. Given dif-31 ferent local characteristics of interest to accumulate, one can 32 obtain various \mathscr{A} fields. A discussion on the relations of some 33 of these \mathscr{A} fields is provided in the later section. Given an \mathscr{A} 34 field, its gradient, $\nabla \mathscr{A}$, and the gradient magnitude can be com-35 puted, which will be used to identify places where the \mathscr{A} field 36 has large changes. 37



Fig. 1: Discontinuity of the \mathscr{A} field at a separatrix connecting a saddle (blue dot) and a source (green dot). The \mathscr{A} field is sampled along the line segment traversing through the separatrix. \mathbf{c}_i indicate the samples along this segment. Case (a) shows a scenario of the discontinuity that the discrete sampling may miss (illustrated by the orange curve), while the discontinuity in case (b) could be captured with sufficient samples.

4. Properties of *A* Fields

It has been discussed before that there are a number of important properties of \mathscr{A} that make it suitable for a number of flow exploration tasks. However, among these properties, the discontinuity in \mathscr{A} still lacks a thorough and informative discussion, leading to the concern about the possible artificial information provided by this discontinuity. In this section, we attempt to resolve this concern.

Uniqueness Given the above definition of the \mathscr{A} field, it is apparent that given any point $(\mathbf{x}, t) \in \mathbb{D}$ (except at fixed points in steady flows), there is exactly one \mathscr{A} value with the specified integration time or length. This is due to the uniqueness of integral curves, i.e., in theory there exists exactly one integral curve passing through any give point except at fixed points. This property allows \mathscr{A} field to achieve full spatial coverage without ambiguity except at fixed points.

Inequality Since the neighboring points that are correlated by the same integral curves may have similar values, the following inequality is expected to hold for the accumulation, as pointed out by Matvienko and Kruger [6].

$$|\langle
abla \mathscr{A}, \mathbf{v}^{\perp}
angle| > |\langle
abla \mathscr{A}, \mathbf{v}
angle|$$

However, due to the influence of different integration times (or lengths), as discussed later, we observe a weaker inequality in practice as below

$$\nabla \mathscr{A}| > |\langle \nabla \mathscr{A}, \frac{V}{||V||} \rangle|$$

This inequality property shows that the patterns observed in \mathscr{A} fields are mostly aligned with the flow direction except at places where \mathscr{A} exhibits certain discontinuous behaviors.

4.1. Revisit Discontinuity in A

In mathematics, a function $f(\mathbf{x})$ defined in \mathbb{M} is said continuous at \mathbf{c} if for every $\varepsilon > 0$, there exists a $\delta > 0$ such that for all $\mathbf{x} \in \mathbb{M} ||\mathbf{x} - \mathbf{c}| < \delta \Rightarrow |f(\mathbf{x}) - f(\mathbf{c})| < \varepsilon$. However, this condition may not be satisfied everywhere in \mathbb{D} by a \mathscr{A} field. Specifically, for a steady vector field that consists of fixed points, the integral curves (or streamlines) passing through them reduce to points.

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Therefore, the obtained A field is not well-defined (i.e. discon tinuous) there.

The second place where \mathscr{A} may exhibit discontinuous behavior is usually at the separation structures of the flow. Consider a smooth vector field, the transition of the (geometric) behaviors of neighboring integral curves is smooth. However, this smooth transition is violated at places where the integral curves have structural changes (e.g. end at different fixed points or two far away locations). Those places correspond to the separation structures in the flow. In many cases, especially in the unsteady 10 vector fields, these separation structures are not unique and sen-11 sitive to the selection of the integration time (see the later dis-12 cussion on this). In contrast, vector field topology is a rigorous 13 notion of the separation structures of steady vector fields, which 14 is defined in infinite long time. In either case, this geometric 15 discontinuous behavior of integral curves may or may not be re-16 flected by the *A* fields that accumulate the local characteristics 17 along integral curves. Figure 1 shows two possible cases where 18 the \mathscr{A} field misses (a) or captures (b) the topological disconti-19 nuity across a separatrix. In case (a), the accumulation values 20 on both sides of the separatrix are similar despite different geo-21 metric behaviors of their associated streamlines. Depending on 22 the seeding location and possibly the numerical error, this dis-23 continuity may be missed. In case (b), the accumulation values 24 on both sides are sufficiently different, capturing the discontin-25 uous geometric behavior across the separatrix. 26

Does this mean that the discontinu-27 ity exhibiting in \mathscr{A} is always a sub-28 set of the separation structures of the 29 vector fields? To answer this ques-30 tion, let us look at another exam-31 ple shown in the inset to the right. 32 This example shows an \mathscr{A} com-33 puted by accumulating the change of 34 the flow direction along the densely 35 placed pathlines for the Double Gyre 36 flow. Beside the well-known sepa-37 ration structure defined as the ridges 38 of the so-called FTLE field, there 39 exists additional discontinuity in the 40



obtained A as highlighted by the arrows. By a close inspection,
this cusp like discontinuity is caused by the abrupt directional
change in the integration of the involved pathlines due to the
two oscillating centers. This behavior has already been reported
in a previous work [37]. This example indicates that the discontinuity in A may correspond to the discontinuous behaviors of
neighboring pathlines other than their geometric characteristics.

Based on the above discussion and analysis, we can conclude 48 that under the numerical error free assumption the discontinuity 49 exhibiting in \mathscr{A} indeed corresponds to the discontinuous geo-50 metric and/or physical behaviors of neighboring integral curves. 51 However, not all this discontinuity can be captured by \mathscr{A} in 52 practice due to the selection of integration times and seeding 53 strategy. With this observation, we argue that the accumulation 54 framework and the resulting \mathscr{A} fields are a simple and effective 55 means to have an approximate overview on the potential dis-56

continuity in integral curve behaviors, which is known relevant to a number of important flow features.

Remark: The highlighted discontinuity in *A* may not provide the precise locations and times where and when it happens. Recall the example shown in the above inset. Although the sharp direction change occurs in a later time in the flow, the discontinuity exhibits in the first time step where those pathlines are seeded. Although this looks like a disadvantage of the accumulation framework and \mathscr{A} fields, it indeed provides a robust way for the seeding and selection of integral curves that may possess interesting behaviors (i.e. the abrupt change of direction) without extracting those features precisely. Nonetheless, there are still cases that knowing the exact local spatio-temporal regions where those features/events occur is necessary. In that case, additional information needs to be utilized in addition to the accumulated value. One possible solution is to study the variation and distribution of the local attributes along integral curves to provide more detailed information about integral curve behaviors, which should be a valuable future direction.

Sensitivity to integration time/length Based on the definition 78 of \mathscr{A} , it is unfortunately sensitive to the specified integration 79 time/length. That means different \mathscr{A} s computed with different 80 integration times/lengths may exhibit different patterns (i.e. different discontinuity structures). Figure 2 provides an example 82 showing the \mathscr{A} fields based on the accumulation of the change of flow direction (aka. signed curvature) of a simple separation 84 flow with different integration times/length. From the results, we see that with a smaller integration length (Figure 2 a), the 86 A field tends to capture the local and short-term flow behaviors. Interestingly, it captures places with large flow curvature. 88 In contrast, a larger integration length may reveal the global and 89 long-term flow behaviors (Figure 2 b), and produce smoother 90 \mathscr{A} fields at the same time. This effect is similar to the observa-91 tion in the convolution process used by the texture-based tech-92 niques [6]. Figure 2 (c) shows the plots of the \mathscr{A} values along 93 two line segments (shown in Figure 2 (b)). As can be seen, the 94 ranges of the \mathscr{A} values on these two sampled segments are not 95 identical. This again can be attributed to the sensitivity of the 96 sampling location on the separation structure and the smeared 97 effect of long integration. In practice, the selection of the integration times/lengths depends on the needs of the applications. 99 If the local characteristic of the flow is of interest, a small in-100 tegration time can be selected, while if the global and structure 101 information of the flow is the focus, a long integration may be 102 used. A similar consideration on the selection of integration 103 time can be seen in the FTLE computation. 104

Average of the accumulated value To avoid the possible artifacts introduced by the number of integration steps, especially when the integral curves are getting closer to fixed points, we also computed $A'_g(\mathbf{x},t) = \frac{1}{t}A_g((\mathbf{x},t_0),t)$ for unsteady flow and $A'_g(\mathbf{x},s) = \frac{1}{s}A_g(\mathbf{x},s)$ for steady flow, which essentially describes the average behavior of the particle along its path. We compare the resulting \mathscr{A} fields with and without this average computa-

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Fig. 2: The influence of the accumulation window size (i.e integration length). (a) shows the \mathscr{A} field computed with the integration length equal 10% of the size of the bounding box of the flow domain, while (b) shows the \mathscr{A} field with the length equal twice of the size of the bounding box. (c) shows the plots of the \mathscr{A} values sampled along two seeding line segments. As can be seen, even they have the same length, the two segments encode different amount of information quantified by the range of the \mathscr{A} values along the segments.



Fig. 3: The A fields computed without (left) and with average (right).

tion and observe that they in general have similar behavior with 2 the difference of some scalar factor (Figure 3). The benefit of using the average value is to enable us to inspect the overall 3 attribute behavior along the integral curves. This can be use-4 ful when studying the behaviors of particles in unsteady flows. 5 However, the difference between the \mathscr{A} values near the discon-6 tinuity tends to become smaller (Figure 3(right)), which may make the identification of these places challenging. Therefore, 8 in most of our experiments, we use the non-average version of the \mathscr{A} fields. 10

5. *A* Field Enabled Flow Exploration and Discussion

Based on the above discussions on the properties of \mathscr{A} fields, 12 we now describe how to utilize this simple accumulation to sup-13 port a number of flow visualization and exploration tasks. Pre-14 vious work has demonstrated that the obtained \mathscr{A} fields can be 15 used to assist the seeding and selection of integral curves and 16 perform flow segmentation. In this section, we demonstrate 17 how to use \mathscr{A} fields and other information derived from the 18 local attributes to perform ribbon and stream surface placement 19 for 3D flow visualization. In addition, we show a new applica-20 tion of \mathscr{A} fields in the visualization of particle-based flow data. 21

Furthermore, we will provide an informal discussion on the relations of certain attributes in terms of the behaviors of their corresponding \mathscr{A} fields, followed by a couple of extensions of the accumulation framework.

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Compute *A* **in practice** The general computation framework 27 for \mathscr{A} has been described in [13]. For self-contained purpose, 28 we briefly describe this framework. We use a uniform dense 29 sampling strategy to avoid any bias under the assumption of no 30 priori knowledge of the data is known. Given any sample point, 31 an integral curve (i.e. a streamline for a steady vector field 32 or a pathline for an unsteady vector field) is computed using 33 the standard Runge-Kutta fourth order integrator (RK4) with a 34 fixed step size. The local attribute values are interpolated at the 35 integration points based on the pre-computed values at the uni-36 form dense samples. It is worth noting that due to the uniform 37 sampling strategy and an axis dependent order, the computed 38 A may possess certain artifacts or numerical errors. To address 39 this, we introduce two additional processes to the original ac-40 cumulation framework. First, we construct a dual grid with the 41 uniform samples as the centers of the grid cells. For each grid 42 cell, a list of the computed integral curves passing through it is 43 recorded. As long as a cell is traversed by an integral curve, 44 this cell is marked visited, and its \mathscr{A} value is computed as the 45 weighted sum of the \mathscr{A} values of the integral curves passing it. 46 The weights are selected based on their distance to the center 47 of the cell. Second, after obtaining the initial \mathscr{A} field, we fur-48 ther smooth it along the flow direction in a similar fashion of 49 the enhanced-LIC approach [38]. That is, we perform another 50 low-pass filtering process along the short integral curves seeded 51 at the sampling points with the \mathscr{A} field as the input. This addi-52 tional smoothing can be very usefully in cases the samples are 53 irregular (i.e. the vertices of the triangle mesh), which is typ-54 ical for surface flows. Figure 4 provide a few examples of the 55 \mathscr{A} fields computed on triangle meshes. In these examples, the 56 streamlines are seeded at the individual vertices of the triangle 57 meshes and integrated sufficiently long (e.g. twice the size of 58 the bounding box of the geometry). Figure 4(a, left) shows the 59 initial accumulated \mathcal{A} , which is not smooth. After performing 60 the aforementioned smoothing, the \mathscr{A} is better aligned with the 61 flow (Figure 4(a, right)). The computation times for \mathscr{A} fields 62 depend on the size of the data, the resolution of the samples and 63 the integration time, which can range from a few seconds (e.g. 64 the 2D steady flow) to 2 hours (e.g. the surface flows) on a PC 65 with an Intel Xeron 1.6GHz CPU and 8GB RAM without any 66 parallelization. 67

5.1. Enhanced Flow Visualization with the Aid of \mathscr{A}

In this section, we demonstrate how to utilize the computed \mathcal{A} and its properties to achieve a number of enhanced visualization for the exploration of various flow data.

5.1.1. Directly Visualizing \mathscr{A} and $|\nabla \mathscr{A}|$

Figure 5 illustrates how to utilize the \mathscr{A} and $|\nabla \mathscr{A}|$ fields computed with different accumulation window sizes for the creation 74



Fig. 4: \mathscr{A} fields of a synthetic surface flow (a), a cooling jacket simulation (b) and a gas engine simulation (c), respectively.



Fig. 5: \mathscr{A} (top) and $|\nabla \mathscr{A}|$ (bottom) fields of a tile of the ocean simulation with different window sizes for accumulation. (a)10% of the size of the bounding box of the data domain; (b) 50%; (c) 2,000%. (d) shows the \mathscr{A} field by accumulating the divergence along streamlines.



Fig. 6: Ribbon placement results for the Bernard data (a) and the tornado data (b), respectively. The left image of each group shows the ribbon placement guided by local helicity information, while the right image shows the placement guided by the derived \mathscr{A} field based on helicity.

of visualizations with different styles. A tile at a specific time
from the surface layer of an ocean simulation data [39] is used.
We accumulate the curl of the flow to compute the A fields
shown in Figure 5 (a-c). A 512 × 512 uniform sampling strategy is used. From the results, we see that with a small accumulation window size, e.g., 10% of the size of the bounding box of
the domain, the resulting A field is not smooth and possesses
patterns that are short but are aligned with the flow, when compared to the background LIC(a, top). Its discontinuity estimated

by the $|\nabla \mathscr{A}|$ field generates a visualization similar to LIC but 10 also highlighting places that have stronger local rotation. With a sufficiently large window, e.g., twenty times the size of the 12 bounding box, the resulting \mathscr{A} is smoother, and its discontinu-13 ity tends to be located around a few vortices in the flow. Figure 5(d) shows an \mathscr{A} field computed by accumulating the diver-15 gence along the streamlines of the same flow. The window size 16 for accumulation is twenty times the size of the bounding box. 17 Compared to the result shown in (c), the divergence-based \mathscr{A} 18

- field tends to highlight the places with strong separation behav-
- ² ior as expected. Additional results can be found in the supple-

³ mental document.

5 Pseudo segmentation via discrete

6 color coding With the spatial cover-

- age property and the inequality property that makes the patterns in the A
- field aligned with flow direction, one
- 10 can easily create a visualization us-
- ing discrete color coding to achieve
 an effect similar to a flow domain
 segmentation. The inset provides an



example of discrete color visualization. Note that there is no actual segmentation is performed in this visualization. However,
a true segmentation may be obtained with this discrete color
assignment as the input [15].

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Remarks: We wish to emphasize that it is because the patterns of the \mathscr{A} fields are aligned with the flow except at fixed points, the direct visualization of \mathscr{A} and $\nabla \mathscr{A}$ fields often provide us an overview of the flow behavior. However, one should also realize that the sensitivity of the \mathscr{A} fields w.r.t the integration times, which may reveal local or global behaviors of the flow in different scales.

26 5.1.2. An *A* Field Guided Ribbon Placement

3D ribbons are known good at representing flow characteristics 27 28 that neither integral curves nor integral surfaces can effectively convey. One example of such flow characteristics is the helicity 29 of the flow that characterizes the rotational behavior around an 30 integral curve. To utilize this information to guide the seeding 31 and placement of ribbons, in addition to aggregating the helic-32 ity along the individual streamlines to obtain an \mathcal{A} , we further 33 derive the standard deviation of the helicity values along each 34 streamlines, denoted by σ . For each candidate seed **p**, we as-35 sign a value of $\mathscr{A}(\mathbf{p}) + \sigma(\mathbf{p})$. Based on this value, we rank all 36 candidate seeds that are uniformly distributed in \mathbb{D} . From the 37 top-ranked seeds, we construct a series of ribbons as the initial 38 set of ribbons. Then, we iteratively insert new ribbons that fill 39 the blank region of \mathbb{D} while keeping a minimum user-specified 40 distance away from other existing ribbons. The similarity met-41 ric introduced by Chen et al. [40] is used to further remove re-42 dundant ribbons that are too similar to the existing ones. Fig-43 ure 6 shows the ribbon placement results using the proposed 44 \mathcal{A} field guided framework. Compared to the ones that are pro-45 duced using only the local attributes (i.e. the initial ribbons are 46 placed at locations with maximum local attribute values), our 47 results tend to generate ribbons with longer length that can pro-48 vide more coherent information about the flow behaviors (i.e. 49 the tornado and the four vortices of the Bernard data are easily 50 identifiable), which is expected. 51

5.1.3. An *A* Field Guided Surface Seeding

An integral surface is the integration of a 1D curve (i.e. seed-53 ing curve) through 3D flows. Compared with the individual 54 integral curves, integral surfaces can more effectively convey 55 3D flow information with the additional visual cues (e.g. light-56 ing, transparency and textures). However, not all integral sur-57 faces are intrinsic. They highly depends on the selection of the 58 seeding position and the shape and orientation of the seeding 59 curve. Generating good seeding curves that can lead to expres-60 sive surface representation of the flow is still a challenging task. 61 With the computed \mathscr{A} and its gradient information, we develop 62 a simple yet effective seeding curve generation strategy. In par-63 ticular, we select a candidate seed \mathbf{p}_c that has the smallest $|\nabla \mathscr{A}|$ 64 value. Let us denote the \mathscr{A} value at \mathbf{p}_c by g. Next, we gener-65 ate a seeding curve starting from \mathbf{p}_c and guided by the curva-66 ture field [41], whose points have A values falling in the range 67 $[g-\delta,g+\delta]$. The obtained seeding curve encodes streamlines, 68 the variation of whose \mathscr{A} values is not larger than δ . Thus, the 69 computed stream surface from this seeding curve is expected to 70 have small variation. In the meantime, we can select a candidate 71 seed \mathbf{p}_c' that has the largest $|\nabla \mathscr{A}|$ value, from which we generate 72 a seeding curve guided by the $\nabla \mathscr{A}$ field. The computed stream 73 surface from this seeding curve is expected to have large varia-74 tion according to the meaning of the $\nabla \mathscr{A}$ field (i.e. it highlights 75 the places where A has large changes). Figure 7 shows two sur-76 faces computed from the two seeding curves constructed using 77 the above two strategies for the flow behind the cylinder data, 78 respectively. The blue surface was generated from a seeding 79 curve with small variation of A values along it, which high-80 lights the boundary of a small vortex bundle next to the cylin-81 der object. In contrast, the red surface was generated from a 82 seeding curve with large variation of \mathscr{A} values. This surface 83 exhibits rich and varying flow behaviors around the boundaries 84 of various vortices. 85



Fig. 7: Comparison of two strategies of seeding curve generation. The red surface is constructed from a seeding curve derived using the small variation strategy, while the yellow is from a seeding curve derived using the large variation strategy. The seed of seeding curve for the blue surface is located inside the bundle, where its $|\nabla \mathscr{A}|$ value is small, i.e., the \mathscr{A} values along this seeding curve for the red surface is located near the boundary of the domain, where the $|\nabla \mathscr{A}|$ value is large, and the variation of the \mathscr{A} values on this seeding curve is also large.

5.1.4. Visualizing Particle-based Data Aided by A

In addition to applying the accumulation framework to the mesh-based vector field data, we also utilize it to aid the visual exploration of the particle-based flow data. Different from the previous examples where the integral curves are computed

to depict the trajectories of mass-less particles. The particles in the particle-based data have mass and their trajectories need not be the integral curves of the corresponding velocity field. Nonetheless, the accumulation framework still applies. In this case, the accumulated value of a particle indeed describes the overall attribute behavior of the particle. Figure 8 shows an *A* field computed based on the change of the moving direction (i.e. a_8) of the particles produced by a dam-breaking simulations computed using the position-based fluid method [42]. From the result we see that particles that hit the boundary have larger change of moving direction, as highlighted by the arrows



Fig. 8: Visualization of an \mathscr{A} field derived from a dam-breaking particle based simulation. Blue means the change of particle moving direction is small, while red mean large. It shows that the particles that hit the boundary have larger change of moving direction, as highlighted by the arrows.

12 5.2. An Informal Study of Relation Among Attributes

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In this section, we conduct an informal study of the relation
 among a number of selected geometric characteristics of the
 integral curves and their corresponding flow properties.

Arc-length vs. velocity magnitude It is not surprising that
these two properties are directly related, as the arc-length of
each segment of an integral curve is determined by the length
of the vector value at the starting point of this segment scaled
by the integration step size, i.e., scaled velocity magnitude.

Winding angle vs. curl Figure 9(a-c) shows a comparison of 23 two \mathscr{A} fields computed by accumulating the change of the flow 24 direction, i.e., winding angle (top) and curl (bottom) for some 25 2D flows, respectively. As can be seen, they exhibit almost 26 identical patterns in the steady case (a-b). This is because curl 27 quantifies the amount of rotation of the flow, i.e., twice the an-28 gular velocity in 2D, at a point in the flow domain, while the an-29 gle difference of the two vectors at two consecutive points along 30 integral curve measures the amount of turning of this curve. If 31 these two points are infinitely close, this angle change will tend 32 to be the curl with the difference of a scale factor. Nonetheless, 33 in general the curl-based \mathscr{A} fields tend to be smoother than the 34 winding angle based \mathscr{A} fields. This is because the curl at any 35 given integration point is obtained via interpolation during the 36 accumulation, while the angle difference between flow vectors 37 is estimated via the angle change of the orientation of the two 38 consecutive line segments of the integral curve, which is subject 39

to numerical error. However, curl-based \mathscr{A} fields may not be 40 able to capture some discontinuity of the geometric behaviors 41 of the integral curves. As shown in Figure 9(c), the cusp-like 42 behavior of pathlines (highlighted by the arrows) is not captured 43 by the curl-based *A* field. This is because this cusp-like behav-44 ior corresponds to sharp angle (i.e., π) change which makes 45 the flow directions before and after the cusp pointing to almost 46 opposite directions, i.e., they are almost co-linear. Thus, the 47 discrete curl computation that is perform while cross product 48 computation will return zero or a very small value. Nonethe-49 less, the relation between curl and the change of flow direction, 50 as well as relation among other vortex identification criteria, 51 such as λ_2 and Q, should be systematically studied to solve the 52 problem of the current lack of a unified definition of vortices. 53



Fig. 9: Comparison of the \mathscr{A} fields computed by accumulating the curl (bottom) and the change of the flow direction (top), i.e., winding angle, respectively. (a) shows the \mathscr{A} fields of a synthetic 2D steady flow. Their corresponding edges are in (b). (c) shows the \mathscr{A} fields of a 2D force duffing system.

FTLE approach vs. accumulating flow vectors along pathlines In addition to accumulating the scalar quantities along the integral curves, we can accumulate vector-valued properties. The resulting \mathscr{A} field is then a vector field. We use this vector-valued accumulation to study the relation of the FTLE computation and a derived scalar field computed from an \mathscr{A} field by accumulating the flow vectors scaled by the integration step size along integral curves. Assume a forward accumulation is considered, i.e., t > 0 in Eq.(1), the resulted vector is an orientation vector that points from the starting point to the end point of the integral curve [11] based on vector calculus, denoted by $V_{SE}(\mathbf{x}) = \boldsymbol{\varphi}_{t_0}^{t_0+t}(\mathbf{x}) - \boldsymbol{\varphi}_{t_0}^{t_0}(\mathbf{x})$ based on the notion of flow map [27]. We store this accumulated vector to the corresponding seeding point of the integral curve, resulting in a vector-valued version of the \mathscr{A} field. It is not difficult to verify that

$$F = \frac{dV_{SE}(\mathbf{x})}{d\mathbf{x}} = \frac{d\varphi_{I_0}^{I_0+I}(\mathbf{x})}{d\mathbf{x}} - I_2$$
(3)

where $\frac{dV_{SE}(\mathbf{x})}{d\mathbf{x}}$ denotes the gradient of the vector-valued \mathscr{A} field, $\frac{d\varphi_{l_0}^{t_0+t}(\mathbf{x})}{d\mathbf{x}}$ denotes the flow map deformation, and I_2 is an 2 × 2 identity matrix. We then compute $s_{t_0}^t(\mathbf{x}) = \frac{1}{t} \ln \sqrt{\lambda_{max}(G)}$, so where $G = F^T F$ -a Cauchy tensor and λ_{max} is the maximum eigen-value of G. This gives rise to a scalar field that seems to



Fig. 10: Comparison of the FTLE fields (top) and a derived fields (bottom) from the \mathscr{A} fields–vector fields defined by V_{SE} for the double gyre flow (a) and the force duffing system (b).

have similar patterns to the corresponding FTLE field computing using the same time window according to Eq.(3). Figure 10 2 provides the comparison of the original FTLE fields (top) and 3 the derived scalar fields (bottom) from V_{SE} for a number of 2D 4 unsteady flows. This indicates that the attribute that quantifies 5 the difference from the starting point to the end point of an inte-6 gral curve encodes the information of flow separation. Nonetheless, the accumulation of vectors using direct vector summation 8 may lead to degeneracy. For instance, accumulating tangent 9 vectors along a closed integral curve results in a zero vector. 10 Therefore, a more appropriate accumulation may be to separate 11 the accumulation of the direction and magnitude components, 12 which may require further investigation. 13

Similarly, one can use this above accumulation to verify the re-14 lation among other vector quantities, such as the difference vec-15 tor between two consecutive flow vectors along integral curves 16 and the acceleration of the flow. In addition, the Jacobian of 17 the vector field-an asymmetric tensor [43], may be accumu-18 lated along the integral curves, which could provide additional 19 insights into the general deformation of the flow particles along 20 their paths. We will leave the detailed discussion of these accu-21 22 mulations to a future work.

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What attribute(s) to accumulate? Based on the existing re-24 sults in the literature, we observe that if the goal is to study 25 the transportation behavior of the flow or the variation of the 26 state of the particles along their paths, then the physical proper-27 ties are typically selected [36]. On the other hand, for the inte-28 gral curve dissimilarity computation, their geometric character-29 istics are usually considered over their physical properties [30]. 30 However, this should not be treated as a general rule, as demon-31 strated by a recent work [28] that the physical properties can 32 also be used to define the distance between integral curves. 33

In addition, different local characteristics may be related to each 34 other by physical principles [8]. Nonetheless, we admit that 35 given certain flow behaviors of interest, there could have more 36 than one characteristic to measure it, and the \mathscr{A} fields that are 37 computed from different characteristics may encode overlap-38 ping flow information. For the specific applications, selection 39 of the appropriate characteristics deserves a detailed and com-40 prehensive discussion as provided in [8], which is beyond the 41 scope of this work. 42



Fig. 11: The $|\nabla\Phi|$ fields based on streaklines for a number of synthetic unsteady flows.

5.3. Extension to Non-integral Curves – Streak Lines

Our accumulation framework for integral curves can be extended to other geometric curves derived from the vector fields, such as streak lines. A *streak line*, $\tilde{s}(t)$, is the connection of the current positions of the particles, $\mathbf{p}_{t_i}(t)$, that are released from position p_0 at consecutive time t_i . Since the meaning of accumulating physical attributes along a streak line



is yet to be clarified, we concentrate on the local geometric characteristics, such as the curvature or the change of the streak line direction. To reduce the memory overload, we limited the number of particles released for each streak line to 200. This may affect the smoothness of streak lines depending on the time window for the computation. To handle boundaries, we simply terminate the computation of a streak line once any of its particles hit a boundary. The inset shows the result for the Double Gyre flow. From this result, we notice two edge segments in both the \mathscr{A} field (top) and the $|\nabla \mathscr{A}|$ field (bottom) (highlighted by the arrows). With a closer look, we find that these two edge segments correspond to the paths of the two oscillating centers. To further verify our conjecture, we perform accumulation along streak lines derived from a number of synthetic unsteady vector fields that possess various moving singularities. Figure 11 shows the results. Not surprisingly, the highlighted ridges in the $|\nabla \mathscr{A}|$ fields of these examples indeed correspond to the paths of the singularities.

Why the \mathscr{A} field computed based on streak links reveal the singularity paths, while the one based on the pathlines cannot? To explain this, let us consider a pathline starting at position \mathbf{x}_0 at time t_i , which defines a flow map $\phi_{t_i}^t(\mathbf{x}_0)$. Once it moves away from \mathbf{x}_0 , information about what happens at \mathbf{x}_0 after t_i is not encoded in that pathline. In contrast, a streak line starting

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from \mathbf{x}_0 and perceived at time $t_i(>t_i)$ is a collection of particles that are released at \mathbf{x}_0 from t_i to t_j . Therefore, it naturally encodes the temporal variation of flow maps passing \mathbf{x}_0 after t_i . As we already showed before, the moving of the singularities will cause the sharp change in the direction of integral curves. This abrupt geometry change is captured by the accumulation of streak line. Nonetheless, we believe additional effort should be made to provide a more rigorous interpretation of the patterns revealed in the streak line based \mathscr{A} fields.

5.4. Comparison with the Eulerian Accumulation 10

To some extent, the above Lagrangian accumulation framework 11 allows us to inspect the aggregated (or overall) behaviors of 12 particles during their advection (especially in the unsteady set-13 ting). In the meantime, we can accumulate (or aggregate) the 14 attribute values measured at the fixed locations but over time 15 to obtain the overall information of the flow at those locations. 16 This scenario shares some similarity with the way of how differ-17 ent weather measurements are collected at those fixed stations. 18 We refer to this accumulation the *Eulerian accumulation*. 19

Figure 12 (a) shows the Eulerian accumulation results of a num-20 ber of attributes for the 2D flow behind cylinder data. Most of 21 these attributes are relevant to the vortical behaviors of the flow. 22 As the vortex street pattern behind the cylinder in this flow is 23 well known (which is also depicted by the texture image of the 24 original flow minus the ambient component), we can clearly ob-25 serve that the obtain \mathscr{A} fields all highlight the regions where the 26 vortices sweep through. In particular, the regions highlighted 27 by the accumulation of acceleration magnitude, λ_2 and the de-28 terminant of the Jacobian clearly highlight the places that the 29 vortex centers go through, which induce two tails in the later 30 part of the domain (highlighted by the arrows). In contrast, the 31 Lagrangian accumulation of the same attributes (Figure 12 (b)) 32 does not provide this overall aggregated information of vortex 33 regions but rather it highlights the oscillating behaviors of the 34 individual vortices. 35

6. Conclusion

In this work, we revisit the Lagrangian accumulation framework for the vector field data exploration. Especially, we pro-38 vide an in-depth and thorough discussion on the properties of 39 the derived \mathscr{A} fields based on the accumulated attributes along 40 integral curves. In particular, we study the discontinuity ex-41 hibiting in the \mathscr{A} fields and analyze its relation to the flow 42 structure. We conclude that the discontinuity structure in the 43 \mathscr{A} fields is aligned with the flow direction and can reveal ad-44 ditional discontinuous behaviors in the flow characteristics that 45 cannot be represented by the conventional flow structure. We 46 also point out that the selection of the integration time in the 47 computation of \mathscr{A} may have great influence to the patterns in 48 \mathcal{A} , which is similar to the computation of the FTLE field of the 49 flow. Properly choosing the integration time can reveal different 50 local (or short-term) and global (or long-term) flow behaviors, 51

respectively. Based on these new insights, we further demon-52 strate how to apply \mathscr{A} fields to achieve a number of enhanced 53 flow data visualizations and explorations. To demonstrate the 54 flexibility of the accumulation framework, we extend it to the 55 study of streak line behaviors, which enables us to discovery in-56 teresting relation between the geometric discontinuous behav-57 iors of streak lines and the paths of moving singularities. Fi-58 nally, we introduce the Eulerian accumulation that aggregates 59 information at fixed locations over time, which enables us to 60 study the aggregated behaviors of the flow in a different way 61 from the Lagrangian accumulation. 62

We believe the accumulation framework and the obtained \mathscr{A} fields representation provide a valuable means to derive aggregated information to provide an overview of the flow behavior and to support various flow exploration tasks. As noted by an expert, the accumulation framework "is relatively straightforward; it is conceivable that application scientists would adopt this technique. I make a point of stating this, since some techniques are so convoluted that it seems inconceivable that end users would adopt them; this work is not in this camp."

Limitations and future work However, there are a number 72 of limitations that the user should be aware of. First, even 73 though we have shown that choosing different window sizes 74 for the accumulation may be employed to generate various vi-75 sualizations, the selection of an appropriate window is highly 76 application-dependent, which may influence both the computational cost and the revealed patterns. Similarly, the sampling strategy could affect the information that can be captured by the \mathscr{A} fields. Second, during the accumulation, the character-80 istic values may cancel each other. For instance, if one accu-81 mulates the change of the flow direction along a symmetric in-82 tegral curve that has the behavior similar to a sine function, the 83 resulted value can be zero. Third, the discussed accumulation is also a dimensionality reduction process (i.e. reducing the 1D 85 information into a single value), which will surely result in information loss. However, this information loss and a solution 87 to reducing it have not been carefully discussed, which we plan 88 to investigate in the future. 89

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Fig. 12: Comparison of Eulerian (a) and Lagrangian (b) accumulations using various attributes of the flow behind cylinder data. Note that the Eulerian accumulation highlights the places where the vortices sweep through, while the Lagrangian accumulation emphasizes the oscillating behaviors of the individual vortices.

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